

# MPC in Statoil

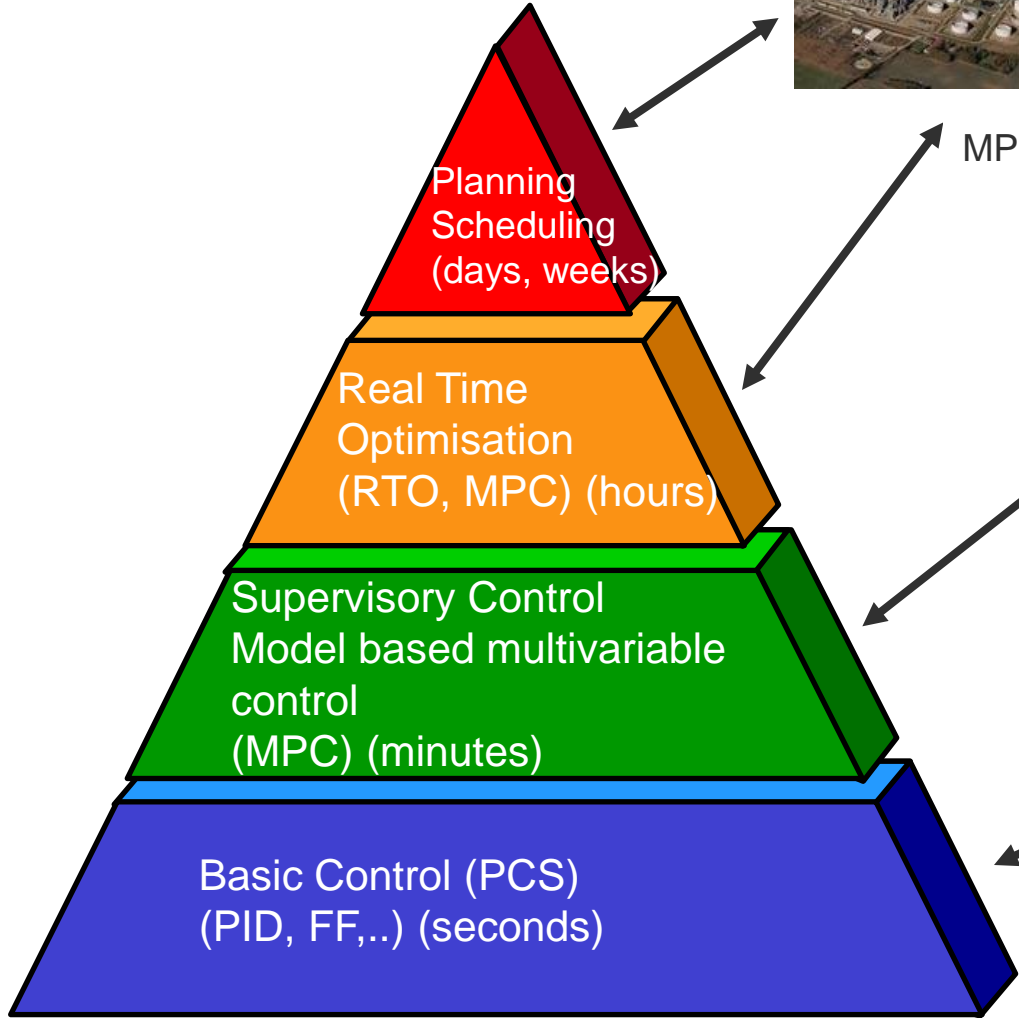
Stig Strand, specialist MPC

Statoil Research Center 93 →

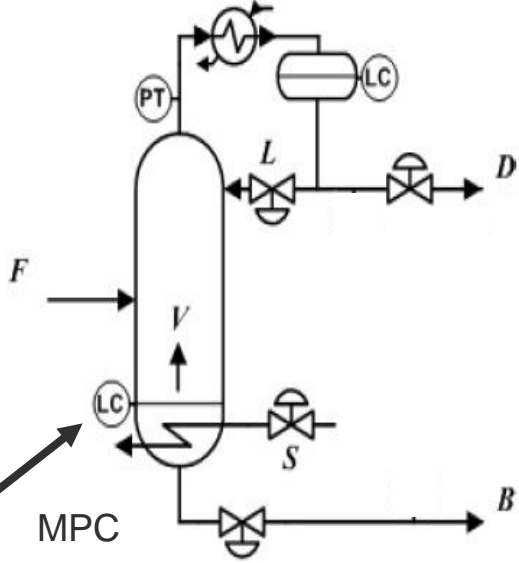
SINTEF Automatic Control 91-93

Dr. ing 1991: Dynamic Optimisation in State Space Predictive Control Schemes

# Process Control – an overview

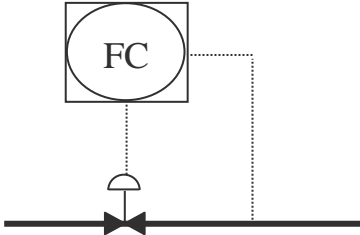


MPC/RTO

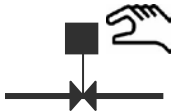


MPC

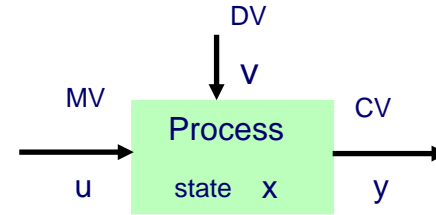
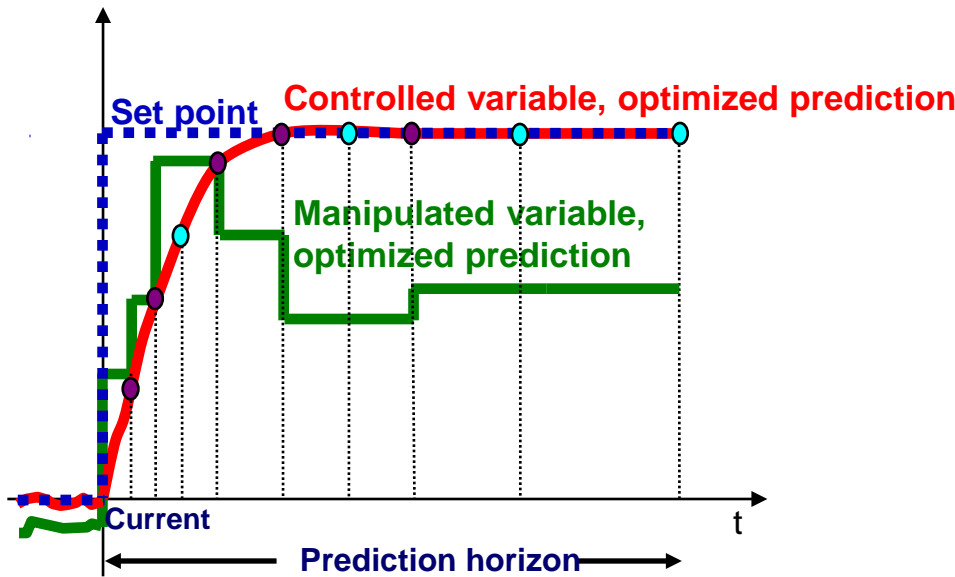
Basic Control



Manual Control



# MPC



$$\min_u \left[ (y - y_{ref})^T Q_y (y - y_{ref}) + (u - u_{iv})^T Q_u (u - u_{iv}) + \Delta u^T P \Delta u \right]$$

$$\dot{x} = f(x, u, v)$$

$$y = g(x, u)$$

$$u_{\min} < u < u_{\max}$$

$$\Delta u_{\min} < \Delta u < \Delta u_{\max}$$

$$y_{\min} < y < y_{\max}$$

$$y = [y_1 \ y_2 \ \dots \ y_n]$$

$$u = [u_1 \ u_2 \ \dots \ u_k]$$

$$\Delta u = [\Delta u_1 \ \Delta u_2 \ \dots \ \Delta u_k]$$

$$\Delta u_i = u_i - u_{i-1}$$

CV soft constraint:

$$y < y_{\max} + RP$$

$$0 \leq RP \leq RP_{\max}$$

$$w * RP^2 \text{ in objective}$$

- MV blocking → size reduction
- CV evaluation points → size reduction
- CV reference specifications → tuning flexibility set point changes / disturbance rejection
- Soft constraints and priority levels → feasibility and tuning flexibility

# MPC Solver - Control priorities

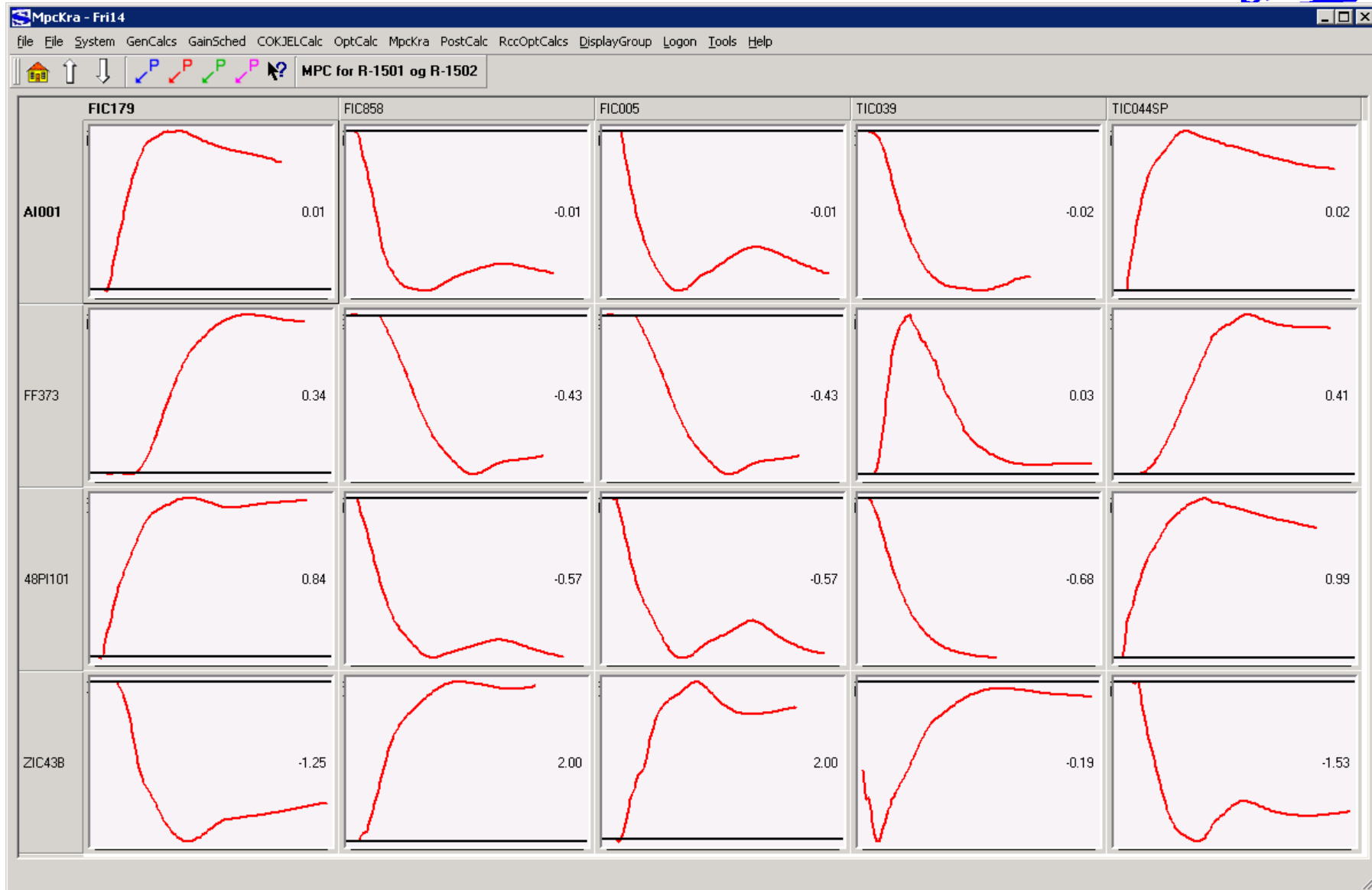
1. MV rate of change limits
2. MV high/low Limits
3. CV hard constraints ("never" used)
4. CV soft constraints, CV set points, MV ideal values: Priority level 1
5. CV soft constraints, CV set points, MV ideal values: Priority level 2
6. CV soft constraints, CV set points, MV ideal values: Priority level n
7. CV soft constraints, CV set points, MV ideal values: Priority level 99

Sequence of steady-state QP solutions to solve 2 – 7 (or NLP if nonlinear models)

Then a single dynamic QP to meet the adjusted and feasible steady-state goals  
(or iterated QP if nonlinear models)

# MPC linear models

SEPTIC

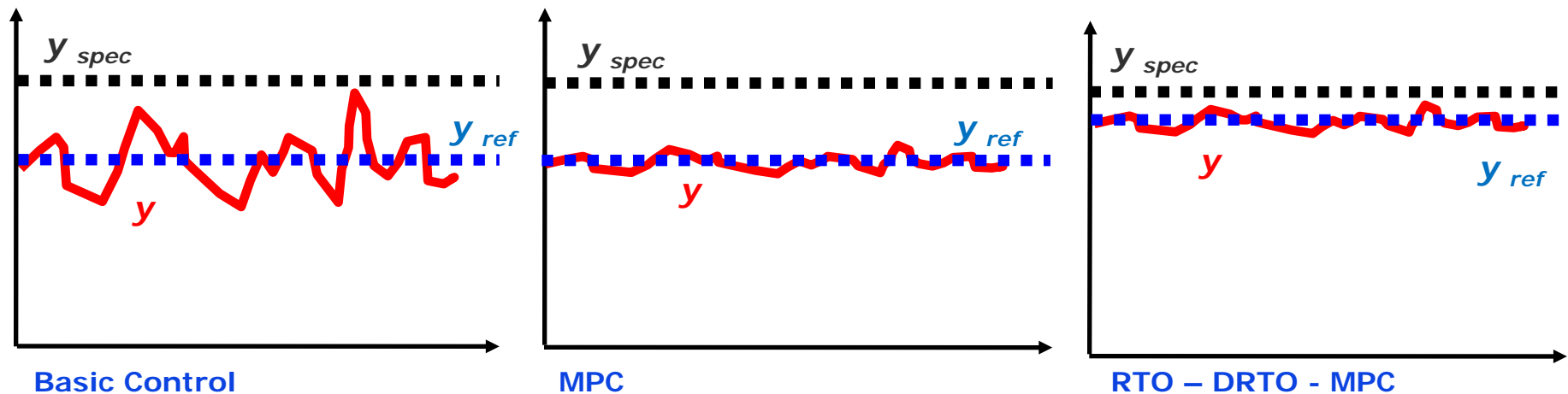


# MPC – nonlinear models

- Open loop response is predicted by non-linear model
  - MV assumption : Interpolation of optimal predictions from last sample
- Linearisation by MV step change
  - One step for each MV blocking parameter (increased transient accuracy)
- QP solver as for experimental models (step response type models)
- Closed loop response is predicted by non-linear model
- Iterate solution until satisfactory convergence

# Contributions of MPC

- Flexible, implements decoupling, feedback and feed-forward
- Improved process response to feed variations
- Improved product quality control
- Maximise capacity, maximise profit, reduce cost
- Respect process constraints related to equipment or environment
- Increased process regularity



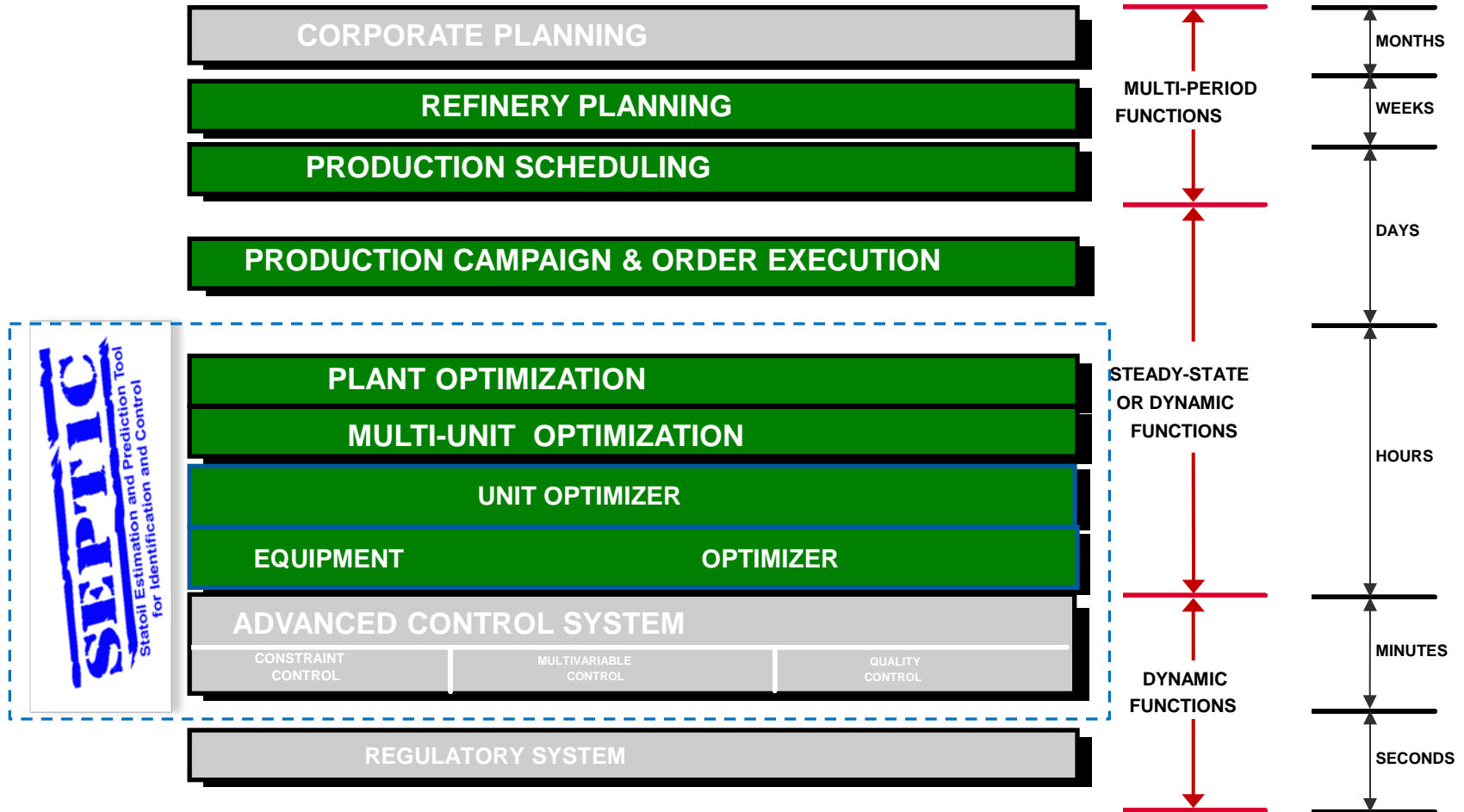
# PROCESS CONTROL

## "The SEPTIC story"

- The in-house developed SEPTIC MPC tool was established in 1997 and has continuously been improved since then, securing state-of-the-art technology
- The process control group at R&D is responsible for SEPTIC, and works with Statoil customers only
- The philosophy with SEPTIC is to implement MPC applications together with the users, which have resulted in;
  - Flexible and quick installations
  - Cheaper solutions than using external vendors
  - Non-bureaucratic way of work
  - Building in-house competence
- In 2013 there are 90 (+/-) SEPTIC applications installed in Statoil

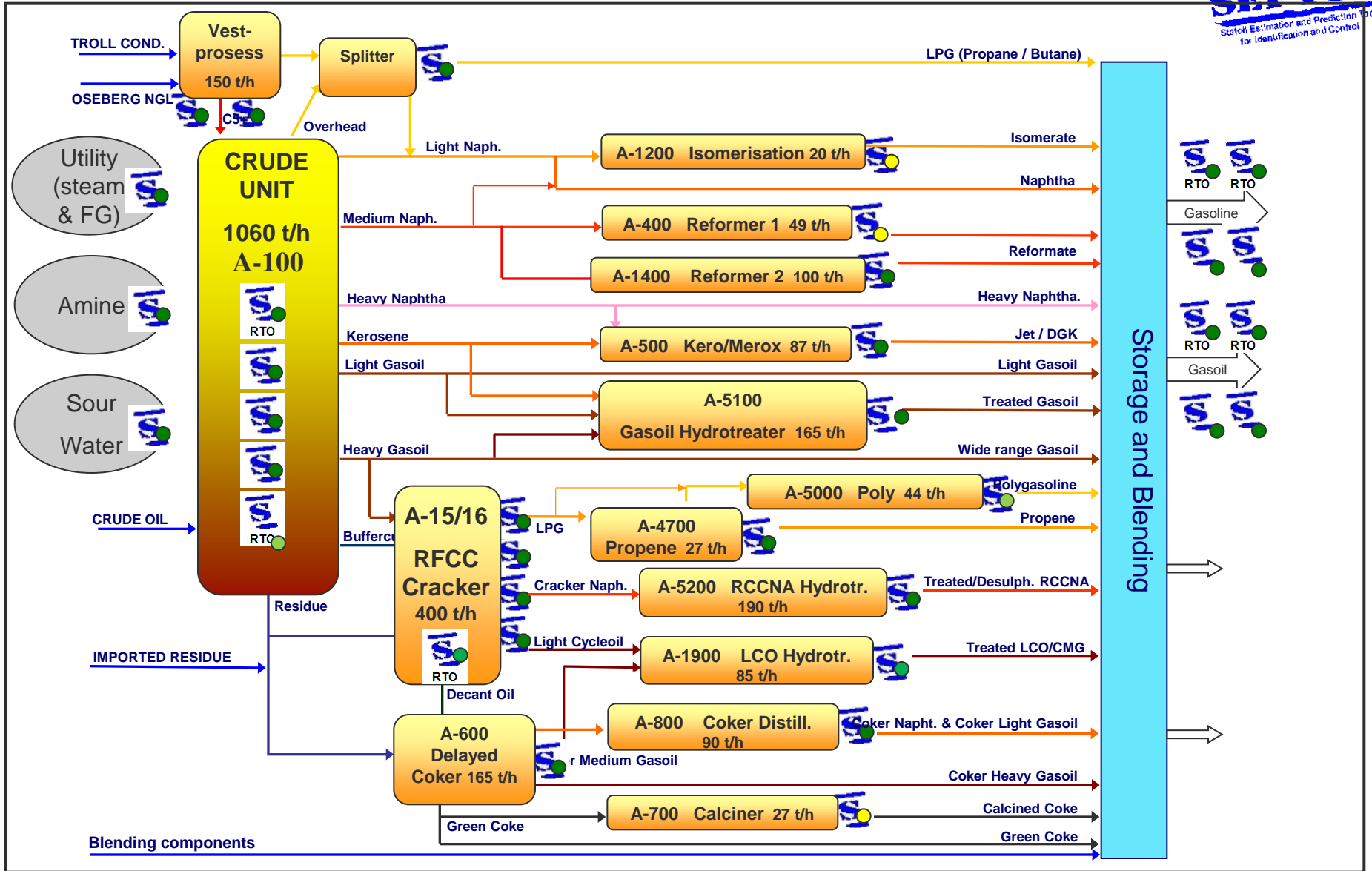


# Planning and control layers in oil refining



# Mongstad Refinery – Septic MPC & RTO

**SEPTIC**  
 Statoil Estimation and Prediction Tool  
 for Identification and Control



Notation:



Running Application



Implementation ongoing



Future Application



# SEPTIC applications Mongstad 2014

| Area                | Unit           | App               | Scope      | #of MV     | #of CV     | Description   |
|---------------------|----------------|-------------------|------------|------------|------------|---|
| A1                  | A-0100         | MPCSPLT           | MPC        | 16         | 24         | Nahta stabilizer and 2 LNA/MNA splitters                          |
| A1                  | A-0100         | MPCFVRM           | MPC        | 12         | 29         | Crude feed & preflash control                                     |
| A1                  | A-0100         | HEXOPT            | RTO        | 8          | 11         | Crude feed heat exchanger optimization                            |
| A1                  | A-0100         | PasBal            | MPC        | 7          | 9          | Crude heaters pass balancing                                      |
| A1                  | A-0100         | ESTT101           | CALC       | -          | -          | Calc app for soft sensors crude unit                              |
| A1                  | A-1100         | MPCNGL            | MPC        | 10         | 9          | 2 paralell LPG/Naphta splitters, Vestprosess pipeline feed        |
| <b>A1</b>           | <b>A-0100</b>  | <b>MPCT101</b>    | <b>MPC</b> | <b>31</b>  | <b>42</b>  | <b>Crude atm distillation, jet fuel unit and gasoil hydrotrea</b> |
| A1                  | A-1100         | MPCLPG            | MPC        | 10         | 11         | C3/C4 splitters Vestprosess                                       |
| A2                  | A-0600         | MPCT601           | MPC        | 8          | 5          | Delayed cocker fractionator                                       |
| A2                  | A-0800         | MPCDES            | MPC        | 4          | 4          | Delayed coker overhead hydrotreating and destillation             |
| B1                  | A-1500         | ESTB1             | CALC       | -          | -          | Calc app for cat cracker  |
| <b>B1</b>           | <b>A-1500</b>  | <b>RCCOPT</b>     | <b>RTO</b> | <b>10</b>  | <b>21</b>  | <b>Optimizer cat cracker</b>                                      |
| B1                  | A-1500         | MpcKra            | MPC        | 11         | 19         | Cat cracker reactor and regenerator control                       |
| B1                  | A-1500         | MpcDes            | MPC        | 12         | 11         | Cat cracker main fractionater control                             |
| B1                  | A-1600         | MPCBUT            | MPC        | 4          | 5          | Cat cracker LPG/Naphta splitter                                   |
| B1                  | A-1600         | MpcAbs            | MPC        | 5          | 8          | Cat cracker fuel gas/heavier splitcontrol                         |
| <b>B2</b>           | <b>A-1900</b>  | <b>A-1900</b>     | <b>MPC</b> | <b>12</b>  | <b>19</b>  | <b>LCO hydrotreating</b>  |
| <b>B2</b>           | <b>A-4000</b>  | <b>A-4000</b>     | <b>MPC</b> | <b>14</b>  | <b>15</b>  | <b>2 parallell amine regenerator control with foaming con</b>     |
| <b>B2</b>           | <b>A-4300</b>  | <b>T-4352</b>     | <b>MPC</b> | <b>3</b>   | <b>5</b>   | <b>Sour water stripper control</b>                                |
| B2                  | A-4700         | MpcPro            | MPC        | 4          | 5          | Cat cracker LPG C3/C4 splitter                                    |
| <b>B2</b>           | <b>A-5000</b>  | <b>A-5000</b>     | <b>MPC</b> | <b>40</b>  | <b>46</b>  | <b>Cat cracker Butene polymerization unit</b>                     |
| B2                  | A-5200         | A-5200            | MPC        | 4          | 12         | Cat cracker naphta hydrotreating                                  |
| B3                  | A-1400         | MPC_R-1400        | MPC        | 6          | 22         | Cat reforming control   |
| <b>B3</b>           | <b>A-21/25</b> | <b>MPC-SG2500</b> | <b>MPC</b> | <b>7</b>   | <b>8</b>   | <b>Steam &amp; Fuel gas network control</b>                       |
| YA                  | A-6200         | LUCBBL1           | MPC        | 10         | 21         | Gasoline blender #1 lineup capacity control                       |
| YA                  | A-6200         | LUCBBL2           | MPC        | 10         | 21         | Gasoline blender #2 lineup capacity control                       |
| YA                  | A-6500         | LUCGOB1           | MPC        | 10         | 19         | Gasoil blender #1 lineup capacity control                         |
| YA                  | A-6500         | LUCGOB2           | MPC        | 9          | 18         | Gasoil blender #2 lineup capacity control                         |
| YA                  | A-6200         | MPCBBL1           | RTO        | 11         | 31         | Gasoline blender #1 product quality control                       |
| YA                  | A-6200         | MPCBBL2           | RTO        | 11         | 31         | Gasoline blender #2 product quality control                       |
| YA                  | A-6500         | MPCGOB1           | RTO        | 10         | 24         | Gasoil blender #1 product quality control                         |
| YA                  | A-6500         | MPCGOB2           | RTO        | 10         | 24         | Gasoil blender #2 product quality control                         |
| <b>Grand Total:</b> |                |                   |            | <b>319</b> | <b>529</b> |   |

Comments or questions?

MPC in Statoil

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